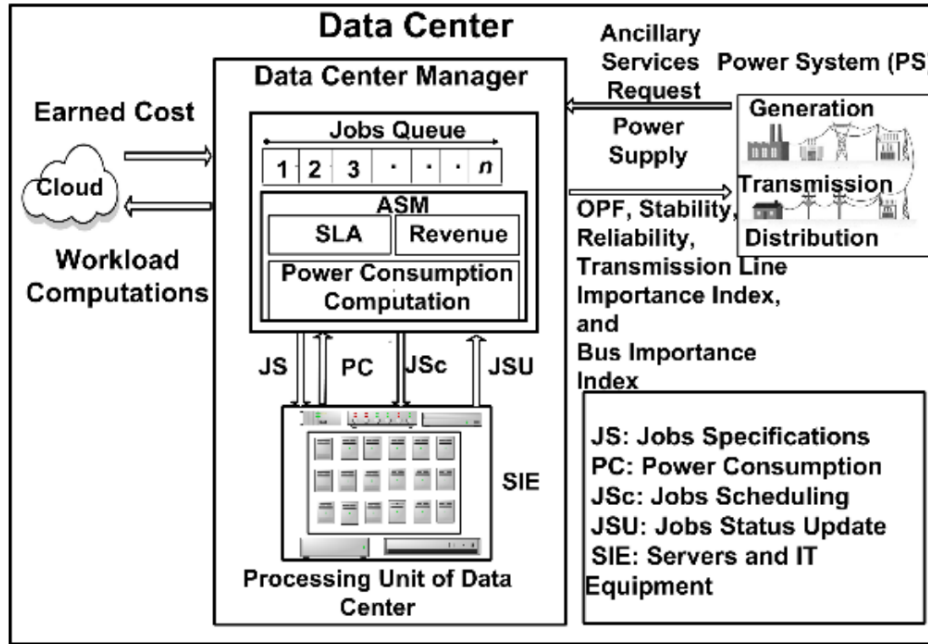


Digital Systems and Microelectronics Emphasis Area

Professor	Classes	Research Interests
Dr. Bryan A. Jones	Senior design	Literate programming, writing to learn to program, embedded systems
Dr. Jean Mohammadi-Aragh	Intro to ECE design I & II	First-year experiences, writing to learn to program, learning analytics, educational 3D viz
Dr. Yaroslav Koshka	Nanoelectronics, Intro to quantum computing, Solid state electronics	Quantum computing, Nanoelectronics
Dr. Chaomin Luo	Computer architecture	Robotics, control systems, computational intelligence, embedded systems
Dr. Yu Luo	Microprocessors	Sustainable wireless networks, cyber-physical systems (CPS), internet of things (IoT), and underwater cognitive acoustic communications
Dr. Samee Khan		Cloud computing, data centers

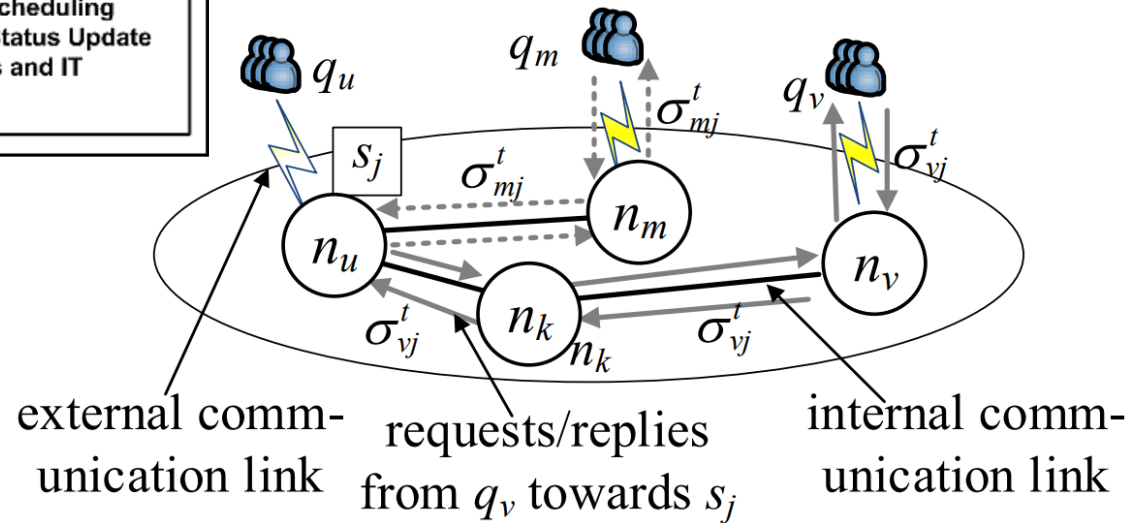
Recommended Courses

- ECE6273 - Microelectronics Device Design
- ECE6713 - Computer Architecture
- ECE6723 - Embedded Systems
- ECE6743 - Digital System Design
- ECE6833 - Digital Communications Networks
- ECE6990-02 - RF Circuit Design
- ECE6990-04 – Introduction to Nanoelectronics
- ECE8990-03 - Wireless Communications
- ECE8990-05 - Asynchronous Design
- Other recommended courses: Digital Controls, Digital Signal Processing, Software Engineering, Power Electronic



Research on Cloud Computing & Data Centers

skhan@ece.misstate.edu



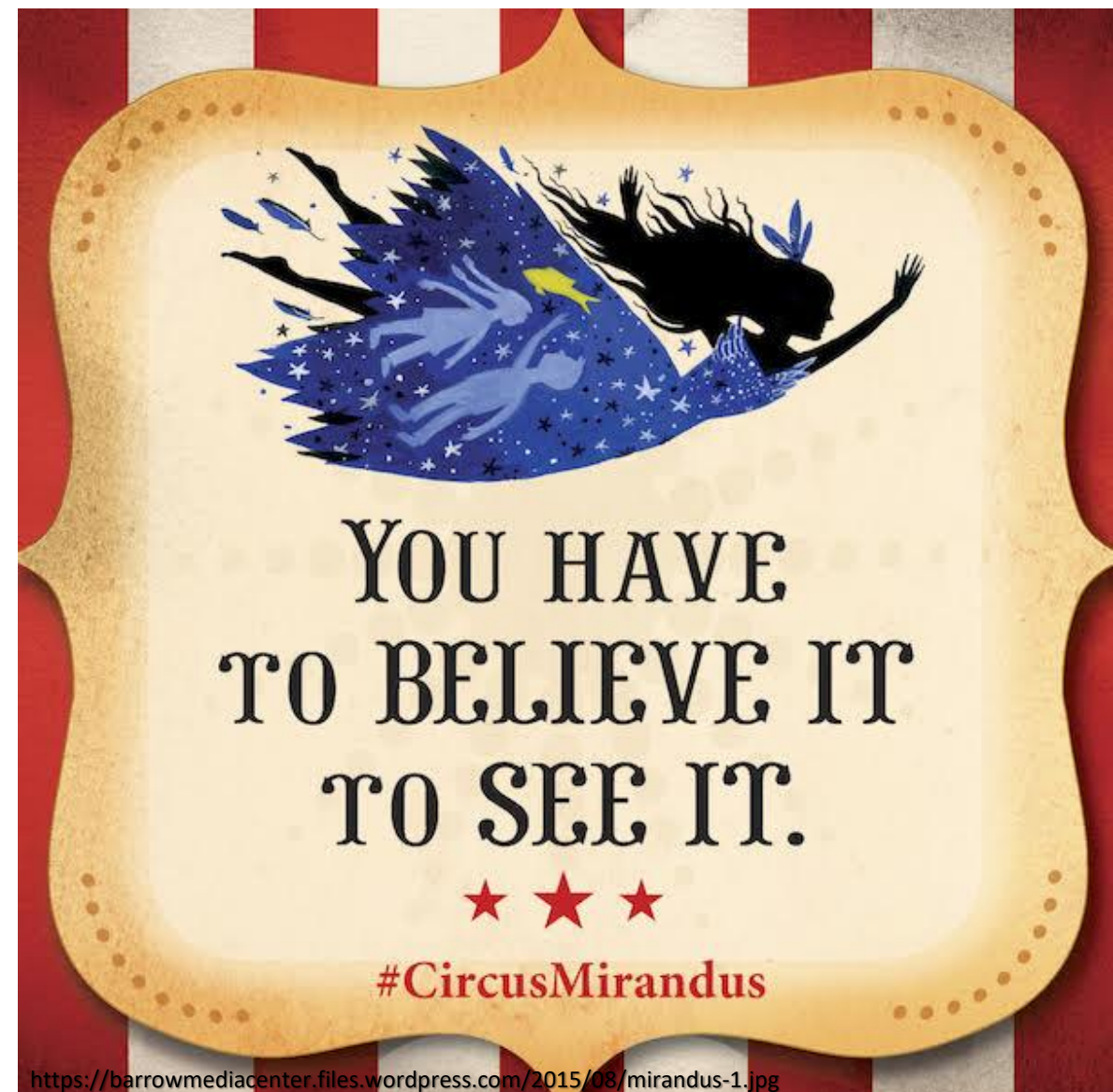
CodeChat: MS Word for developers

What do you believe about your code?

“Now faith is confidence in what we hope for and assurance about what we do not see.” – Hebrews 11:1

What you believe about your code changes the way you create it.

- Experience drives belief.
- Test-driven design is better.
- A program is a document.



```

xc16_as.py  asm.py  wscript.py  options
pic24_asm_to_c > _sources > build > waf > wscript.py > options
17  #
18  # *****
19  # |docname| - Waf build script for in-class examples
20  # *****
21  # This is invoked by ``wscript``.
22  #
23  # Imports
24  # =====
25  # These are listed in the order prescribed by `PEP 8`
26  # <http://www.python.org/dev/peps/pep-0008/
  # imports>`.
27  #
28  # Standard library
29  # -----
30  import os.path
31  from os import mkdir
32  from pathlib import Path
33  import subprocess
34  import zipfile
35
36  # Local application imports
37  # -----
38  from waf.lib import Logs, Utils
39  from waf.lib.Errors import WafError
40  from waf.lib.TaskGen import after_method, feature
41
42  # Local imports
  #

```

CodeChat

Dr. Bryan A. Jones,
bjones@ece.misstate.edu

wscript.py - Waf build script for in-class examples

This is invoked by `wscript`.

Imports

These are listed in the order prescribed by [PEP 8](#).

Standard library

```

import os.path
from os import mkdir
from pathlib import Path
import subprocess
import zipfile

```

Local application imports

```

from waf.lib import Logs, Utils
from waf.lib.Errors import WafError
from waf.lib.TaskGen import after_method, feature

```

Local imports

```

from runestone.lp.lp_common_lib import (

```

Build complete.

Error(s): 0, warning(s): 0

Ln 88, Col 77 Spaces: 4 UTF-8 CRLF Python [off]



main

```
int main(void) {
```

Setup

```
configBasic(HELLO_MSG);  
CONFIG_LED1();  
config_pb1();
```

Line A: Start with the LED off.

```
LED1 = 0;
```

Main loop

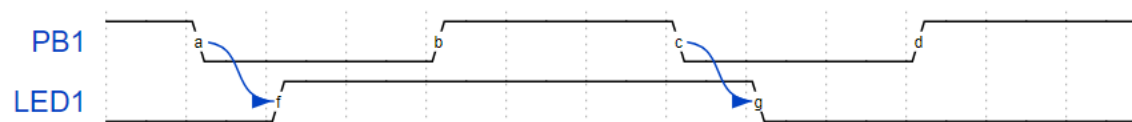


Fig. 2.12 A copy of Fig. 2.10, to help illustrate the operation of the code below.

```
while (1) {  
    test_main();
```

This function returns after edge a.

```
wait_for_press();
```

A few instructions later, at edge f, this line toggles the LED.

```
LED1 = !LED1;
```

This function returns after edge b; the process starts again.

```
wait_for_release();
```

```
}
```

```
return 0;
```

```
}
```

Dr. Bryan A. Jones,
bjones@ece.misstate.edu



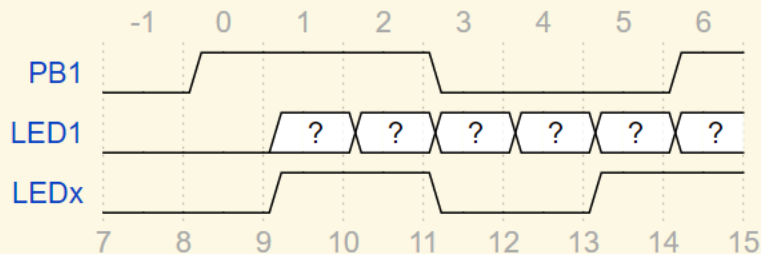
Assessment

Dr. Bryan A. Jones,
bjones@ece.misstate.edu

Q-1: What waveform would be produced by the following code snippet in `main()` ?

```
1 while (1) {}  
2 // Toggle when the pushbutton is **released**.  
3 if (PB_RELEASED()) {  
4     LED1 = !LED1;  
5 }  
6 }
```

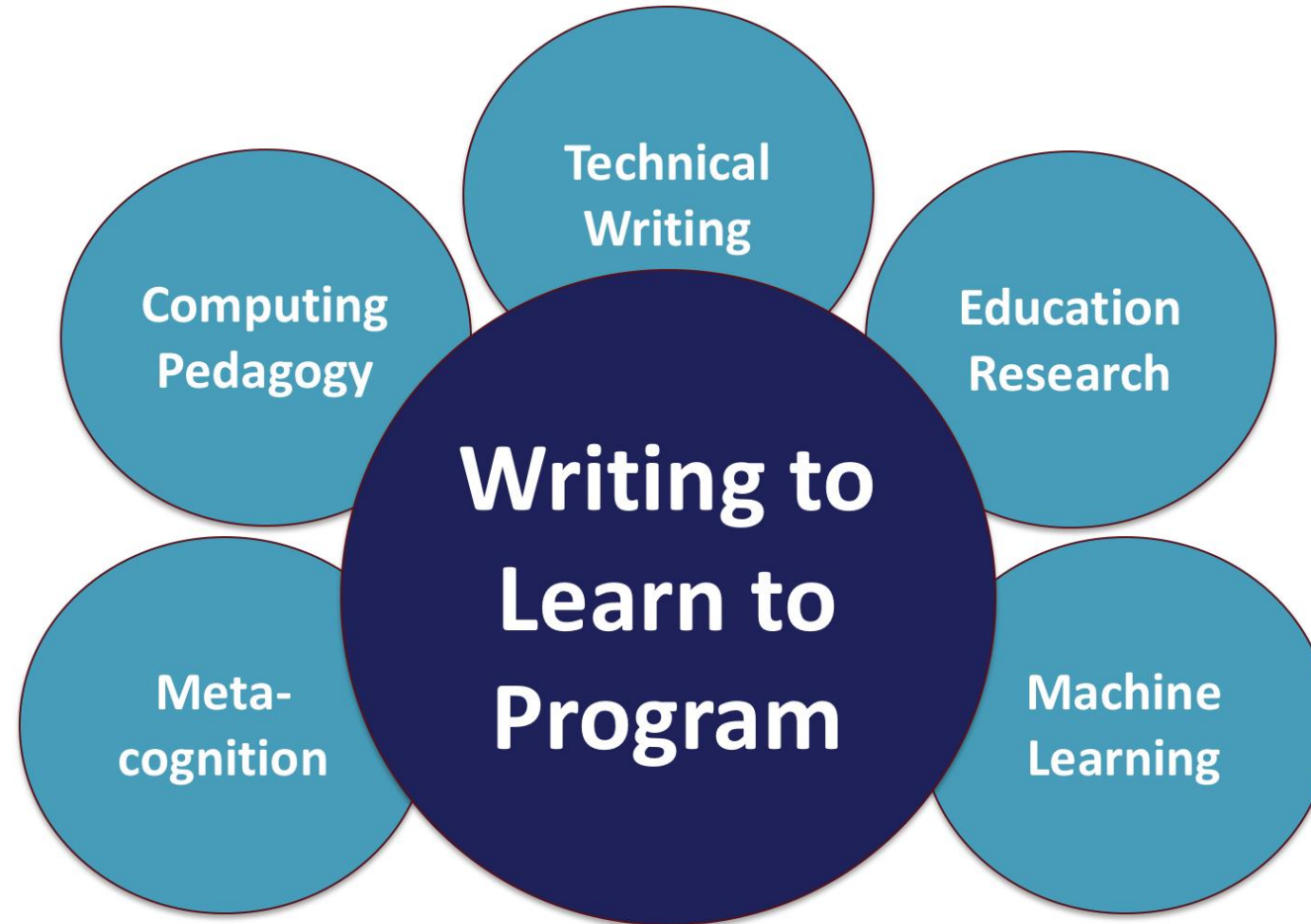
Answer with an six-character string of 1s and 0s, giving the value of LED1 at time periods 1–6. For example, and answer of `110011` produced the LEDx waveform. Hint: at time 7 and 8, the pushbutton is pressed. Therefore, the LED remains unchanged. The pushbutton is released at the time 9, which will cause the LED to toggle at time 1.



Check me

Compare me

Example #1: Writing to Learn to Program



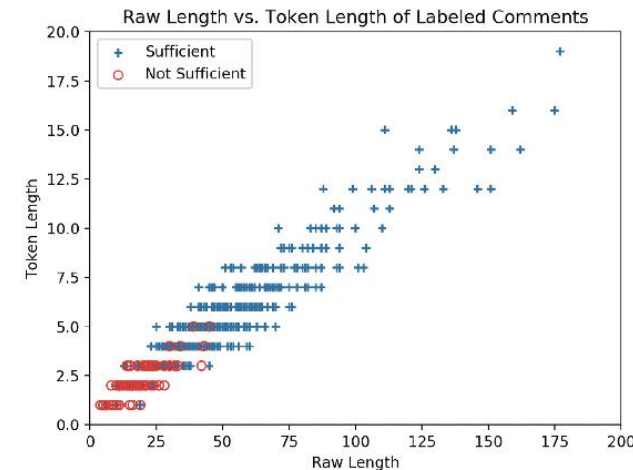
Writing makes thinking visible.

Example #1: Writing to Learn to Program



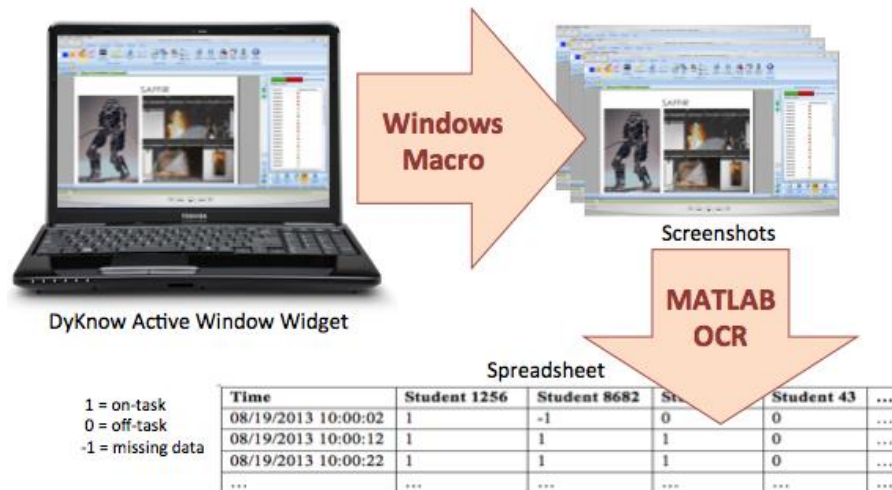
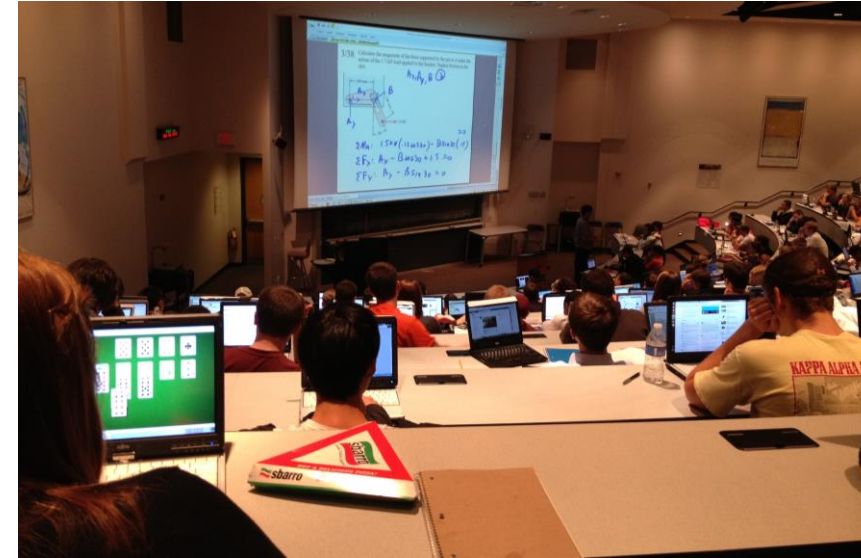
Multinomial Naive Bayes

Random Forest

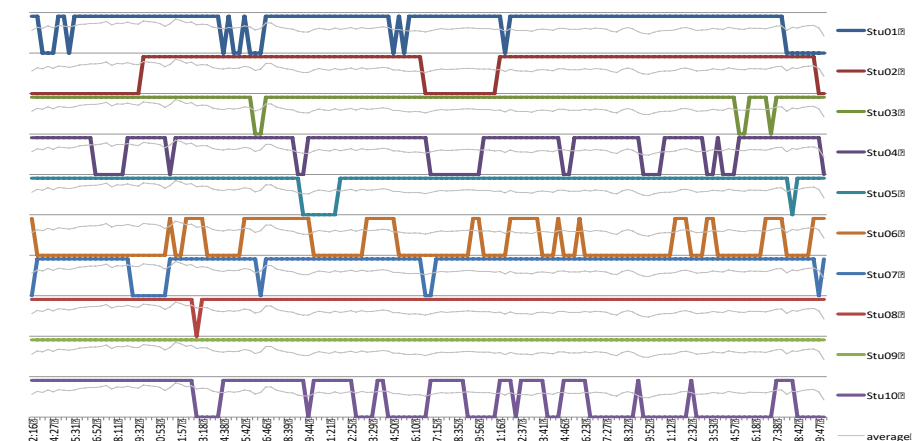


Machine Learning to Classify Source Code Comments in Real-time

Example #2: Impact of Classroom Computers on Learning



Attention in a 50-min 270-Seat Lecture



Example #3: Using 3D Weather Data to Teach Computational Thinking to 7th Graders

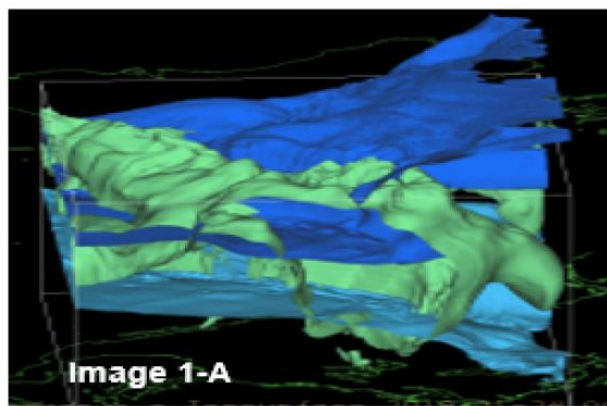
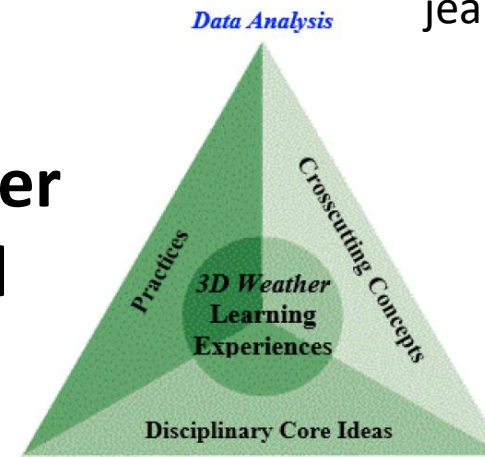


Image 1-A

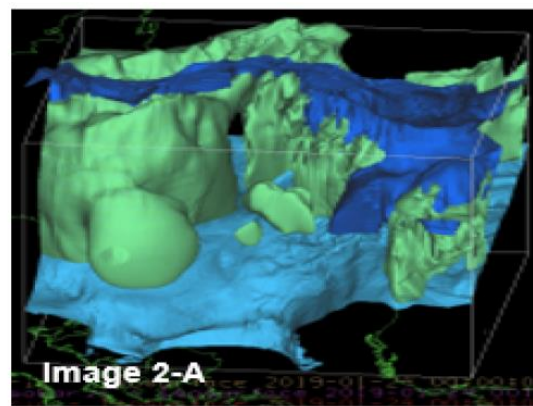


Image 2-A

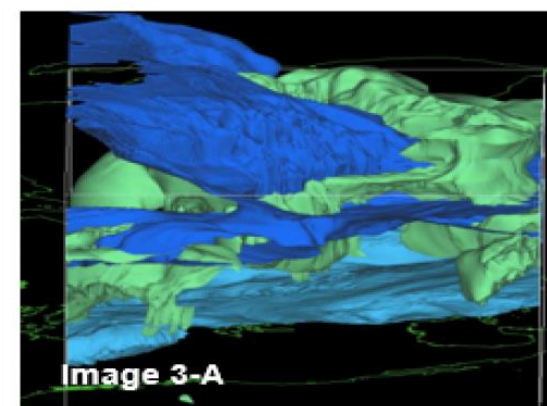


Image 3-A

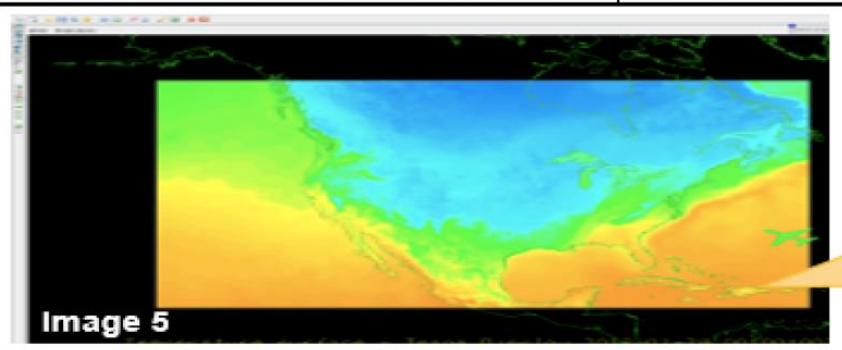
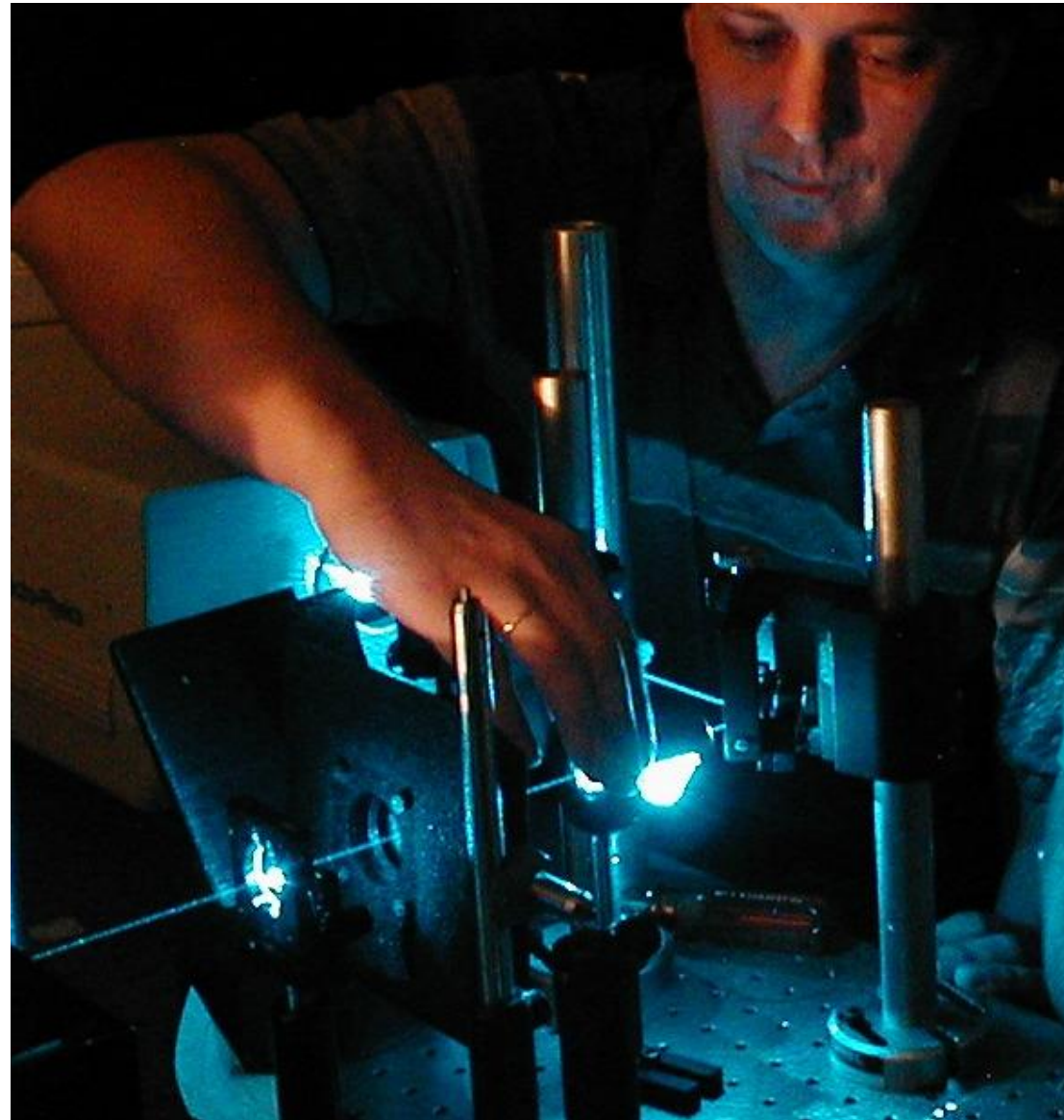


Image 5

Image 5 shows a 2D Image of temperature at the surface typical of television representation of weather. While communicating cold, it provides no information about the structure of the atmosphere causing the event.

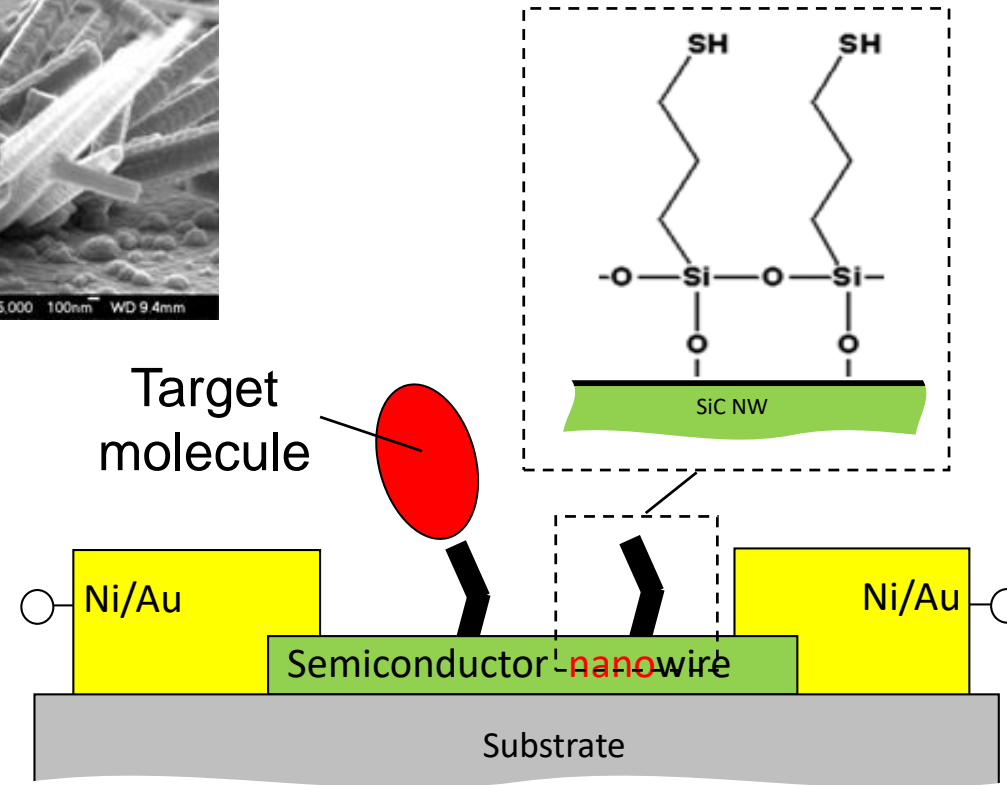
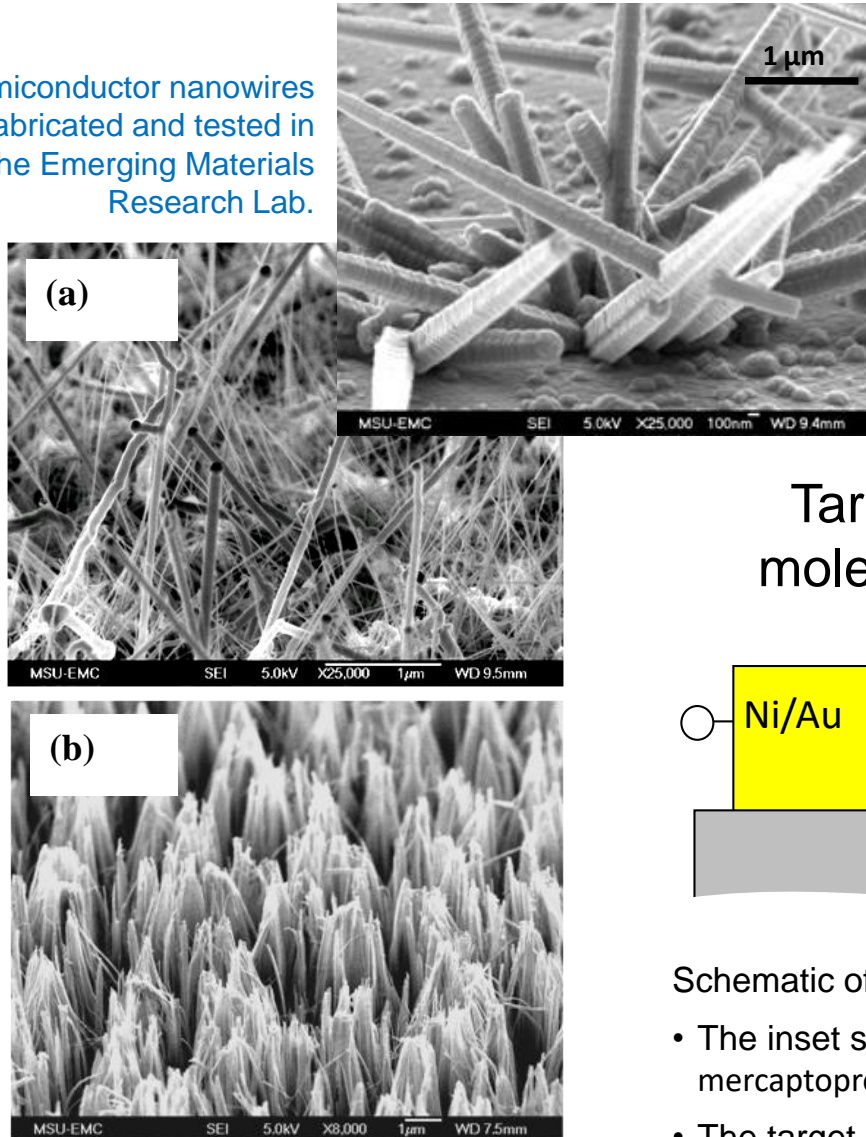
Optical characterization lab



Nanoelectronics

multidisciplinary research targeting emerging biomedical applications

Semiconductor nanowires
fabricated and tested in
the Emerging Materials
Research Lab.



Schematic of a SiC **nanowire field-effect transistor** used as a biosensor.

- The inset shows the surface of the nanowire functionalized with mercaptopropyl trimethoxysilane (MPTMS) as an example.
- The target molecule detected by the device could be a **cancer cell**.

Bio-inspired Autonomous Robots, Embedded Systems and Intelligent Control

Chaomin Luo, Ph.D., Associate Professor

Associate Editor of International Journal of Robotics and Automation

Associate Editor of International Journal of Swarm Intelligence Research

Associate Editor of IEEE Transactions on Cognitive and Developmental Systems

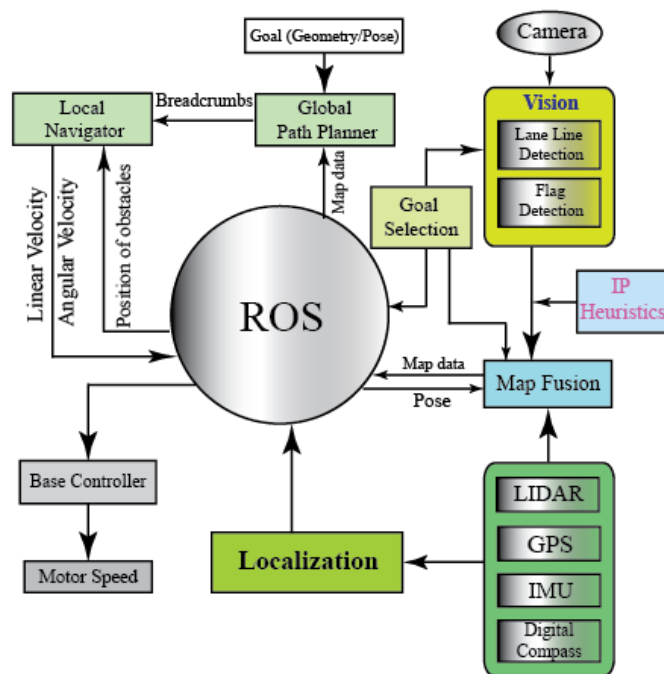
Department of Electrical and Computer Engineering

Mississippi State University

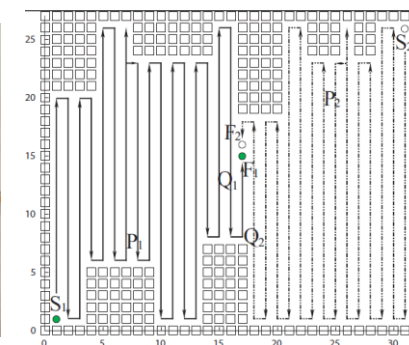
Mississippi, USA

Autonomous Robots

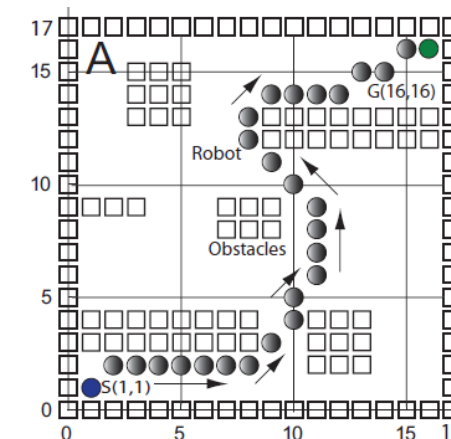
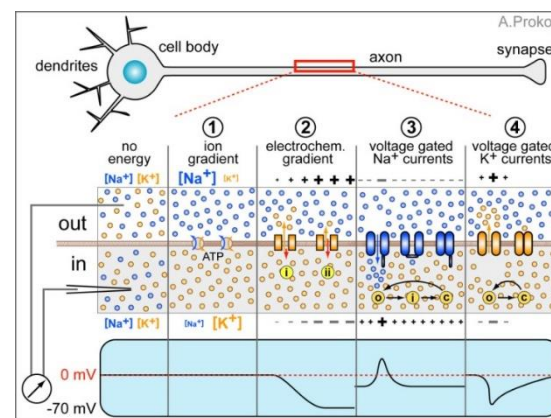
- **Autonomous Robot Systems**
 - Motion planning, navigation, motion control
 - Localization; sensor data fusion; robot vision
 - Hardware and software for mobile robots
 - Collaborative robots (Multi-robot)
- **Machine Learning (Computational Intelligence) for Robotics Systems**
 - Biologically inspired neural networks
 - Evolutionary Computation (genetic algorithms)
 - Immune System Algorithms
 - PSO, Ant colony optimization (ACO)
 - Q-learning, Deep reinforcement learning
 - Deep learning, clustering, reasoning...
 - Optimization (convex programming for engineering)



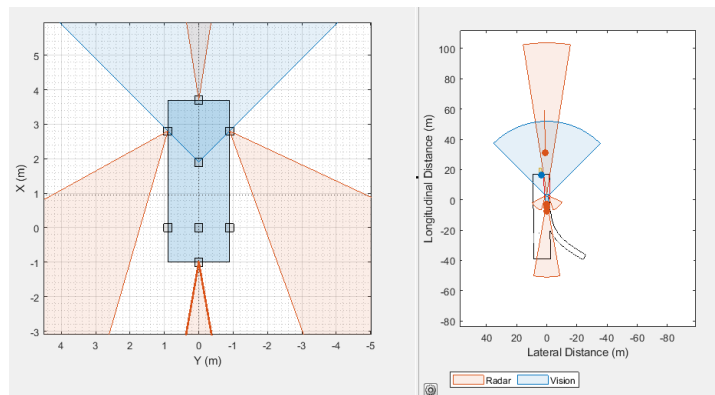
Robot sensor configuration of ROS systems



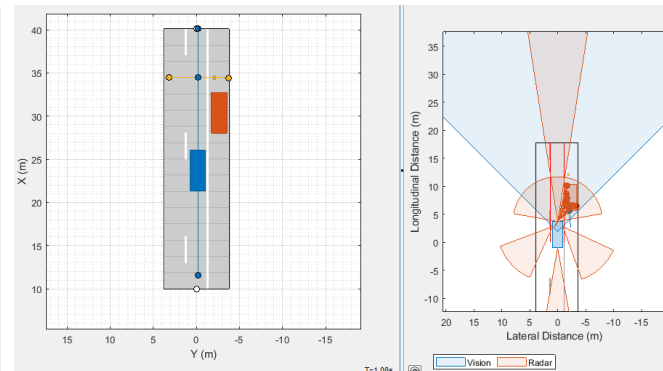
Multi-robot for environment exploration



Bio-inspired neural network model for navigation



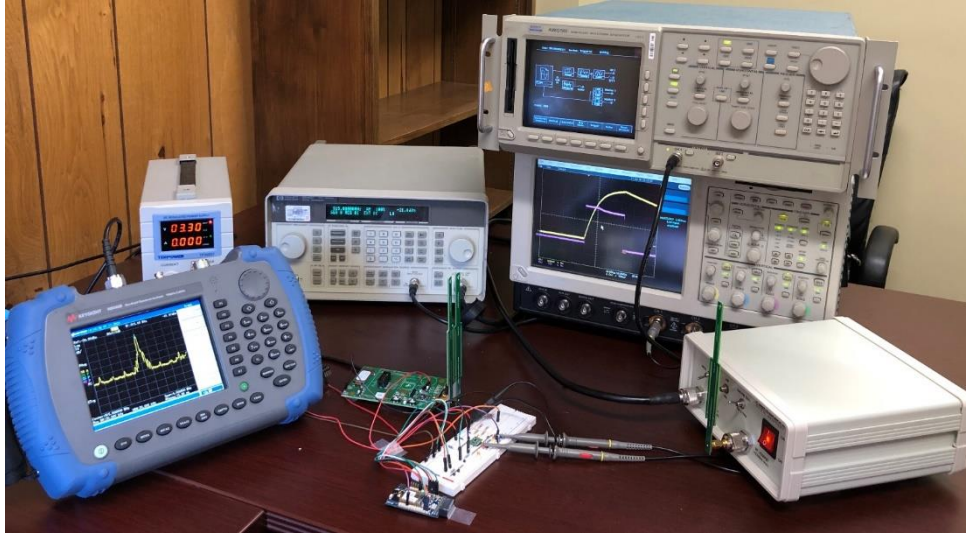
Sensor Data Fusion



Connected and Autonomous Vehicle Systems (CAVs)



Energy Harvesting Wireless Communication Networks



- Harvest radio energy from environment
- Semi-perpetual operations & wireless communications
- Event detection, environmental monitoring, and data collection

IoT for Underwater Exploration

- Detect coexistence of marine animals
- Share underwater acoustic channel with marine animals
- Environment-friendly communications

